

Bridgeland Stability Conditions For Curves and Surfaces.

Chirantan Chowdhury.

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Motivation and development.

Bridgeland

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Triangulated categories and t -structures.

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Note: $\text{Coh}(X)$ is an abelian subcategory of $\mathcal{D}(X)$. Are there any other abelian subcategories of $\mathcal{D}(X)$? Yes, they can be constructed by t -structures.

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A t -structure $(\mathcal{D}^{\leq 0}, \mathcal{D}^{\geq 0})$ on \mathcal{D} is said to be *bounded* if for every object $E \in \mathcal{D}$, we have $E \in \mathcal{D}^{\leq n} \cap \mathcal{D}^{\geq -n}$ for $n \gg 0$.

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Before moving into the stability condition, let us recall the definition of Grothendieck groups and Numerical Grothendieck groups.

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Let X be a smooth projective variety over \mathbb{C} as before. Define the **Grothendieck group** of X denoted by $\mathcal{K}(X)$ as the free abelian group generated by elements of $\mathcal{D}^b(X)$ modulo the relations $[E^\bullet] = [F^\bullet] + [G^\bullet]$ for any distinguished triangle

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We have the **Euler-Poincare** pairing defined as

$$\chi : \mathcal{K}(X) \times \mathcal{K}(X) \rightarrow \mathbb{Z}$$

as

$$\chi(E^\bullet, F^\bullet) = \sum_{i=1}^n (-1)^i \dim_{\mathbb{C}}(\text{Hom}(E^\bullet, F^\bullet[i])).$$

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The **Numerical Grothendieck** group $\mathcal{N}(X)$ is defined as $\mathcal{K}(X)/\mathcal{K}(X)^\perp$ where the \perp is respect to χ .

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Definition

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$$Z(E) \text{ lies in } \mathbb{H} \cup \mathbb{R}_{<0}.$$

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The *phase* of an object $E \in \mathcal{A}$ with respect to a stability function Z is defined by $\phi(E) := \frac{1}{\pi} \arg(Z(E))$.

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An object $0 \neq E \in \mathcal{A}$ is said to be *(semi)stable* if $\forall A \subset E$ subobjects, we have $\phi(A) \leq \phi(E)$.

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It turns out that semistable objects of Z are the semistable sheaves.

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$$\begin{array}{ccc} 0 = E_1 & \xrightarrow{\quad} & E_2 \\ & \nwarrow \quad \swarrow & \\ & A_1 & \end{array} \quad \cdots \quad \begin{array}{ccc} E_{n-1} & \xrightarrow{\quad} & E_n = E \\ & \nwarrow \quad \swarrow & \\ & A_n & \end{array}$$

such that $A_j \in \mathcal{P}(\phi_j)$ for all j .

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Deformation property of stability conditions.

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$$v : K(\mathcal{D}) \rightarrow \Lambda$$

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Thus, for curves it is a complex manifold of dimension 2 as $\mathcal{N}(X)$ is of dimension 2.

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Deformation property of stability conditions.

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Sketch of the proof.

① Firstly, we define topologies on the following collections:

- ① the ring $\mathrm{Hom}(\Lambda, \mathbb{C})$.
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- 5 Finally, we show that we can reduce to the case where the assumption can be made.



Stability conditions on surfaces.

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As stated before, we need a way to construct new t -structures for the case of higher dimensions. Here X is a smooth projective surface. This is done by tilting of abelian categories. At first, we define what is a torsion pair.

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where we define $\mu_i = \mu_F(E_i/E_{i-1})$ (here F is an ample divisor needed for definition of stability). Also, we have

$$\mu_{F-\max}(E) = \mu_1 > \mu_2 > \dots > \mu_n(E) = \mu_{F-\min}(E).$$

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$$\mathcal{A}_{(D,F)}^\# = \{E^\bullet \in \mathcal{D}^b(X) \mid H^i(E^\bullet) = 0, \forall i \neq 0, -1, H^{-1}(E^\bullet) \in \mathcal{F}, H^0(E^\bullet) \in \mathcal{T}\}$$

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So we have a new heart. Now we need to construct a stability function.

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That's all folks!!